

Best Basis

(A first look)

With the LOT, we have a very flexible framework for partitioning the real line and analyzing each segment (local trig. series in each interval)

Natural question: Given a signal $f(t)$, what is the "best" partition?

To answer this question, we will restrict ourselves to dyadic partitions and a very particular meaning of "best".

Dyadic Partitions

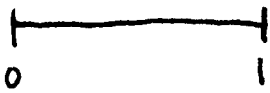
A dyadic partition of an interval is any partition we can generate by recursively splitting subintervals in half.

Associated with each dyadic partition is a binary tree.

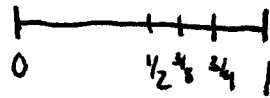
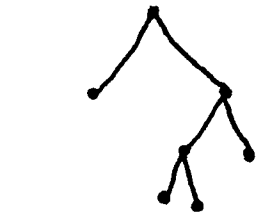
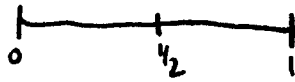
Examples.

Partitioning the interval $[0,1]$
Dyadic partitions (and associated trees)

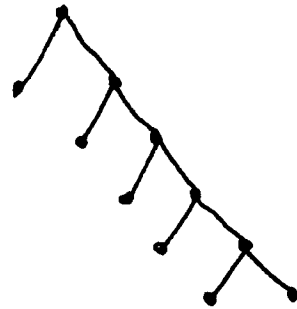
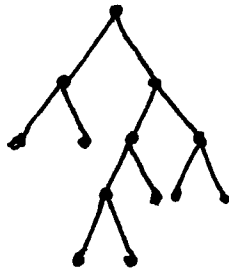
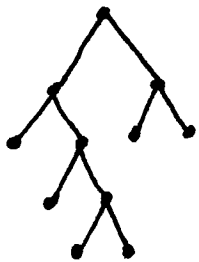
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(interval itself)



What do the partitions for these trees look like?



Note: To correspond to a dyadic partition each parent in the tree must have either 0 or 2 children.

Nodes with 0 children are called leaves.

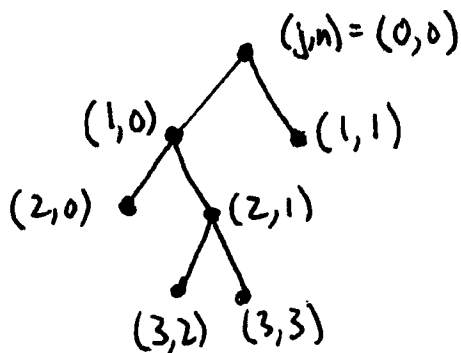


Each node in a dyadic tree can be indexed by a scale j and a shift n .

$$0 \leq j \leq J$$

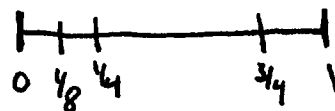
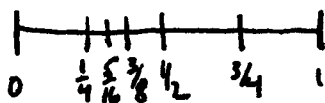
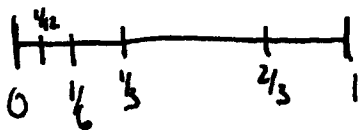
$J = \text{maximum depth of tree}$

$$0 \leq n \leq 2^j - 1$$



The children of a node indexed (j, n) are indexed by $(j+1, 2n)$ and $(j+1, 2n+1)$.

Exercise Which of these are not dyadic partitions?



Given a binary tree, the endpoints of the corresponding partition of $[0,1]$ are

$$a_{j,n} = n \cdot 2^{-j} \quad \text{for each leaf } (j,n)$$

Along with a partition, each (valid) binary tree corresponds to a different orthogonal decomposition of $L_2([0,1])$.

Take $\eta \leq 2^{-j-1}$

For a dyadic interval $[a_{j,n}, a_{j,n+1}] = [n \cdot 2^{-j}, (n+1) \cdot 2^{-j}]$

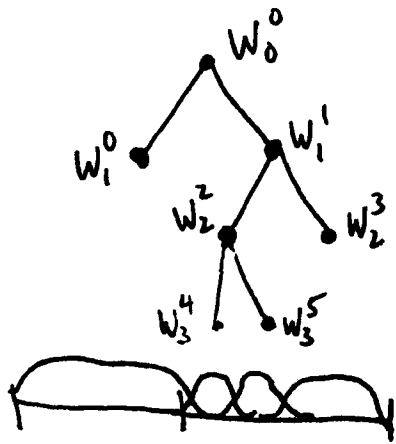
define the window

$$g_{j,n}(t) = \begin{cases} \beta\left(\frac{t-a_{j,n}}{\eta}\right) & t \in [a_{j,n}-\eta, a_{j,n}+\eta] \\ 1 & t \in [a_{j,n}+\eta, a_{j,n+1}-\eta] \\ \beta\left(\frac{a_{j,n+1}-t}{\eta}\right) & t \in [a_{j,n+1}-\eta, a_{j,n+1}+\eta] \\ 0 & \text{otherwise} \end{cases}$$

and the subspaces W_j^n as before

$$\left(f \in W_j^n \iff f(t) \text{ can be written } f(t) = g_{j,n}(t) \cdot h(t) \right.$$

where $h(t)$ is symmetric around $a_{j,n}$
and anti-symmetric around $a_{j,n+1}$



We can write

$$L_2([0,1]) = \bigoplus_{(j,n) \in \text{Leaves}(\mathcal{T})} W_j^n$$

for any valid binary tree \mathcal{T} .

Also, it is not hard to see that the children spaces W_{j+1}^{2n} , W_{j+1}^{2n+1} orthogonally decompose the parent space W_j^n . That is

$$W_j^n = W_{j+1}^{2n} \oplus W_{j+1}^{2n+1}$$

We know an orthobasis for each W_j^n , we will denote

it

$$B_j^n = \left\{ g_{n_{ij}}(t) \cdot \sqrt{2^{j+1}} \cdot \cos \left[\pi \left(k + \frac{1}{2} \right) \cdot \frac{t - a_{n_{ij}}}{2^{-j}} \right] \right\}_{k \in \mathbb{Z}}$$

So given a valid binary tree \mathcal{T} , we have an orthonormal basis for $L_2([0,1])$

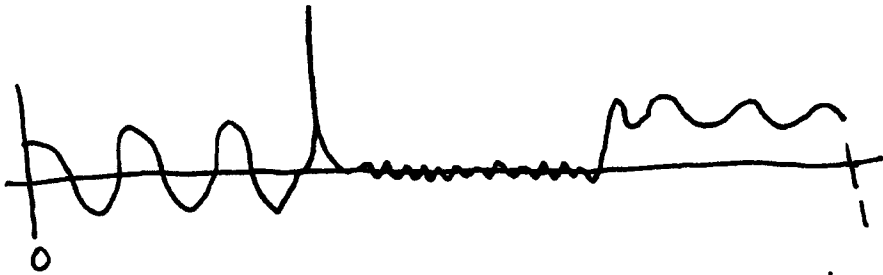
$$B_{\mathcal{T}} = \bigcup_{(j,n) \in \text{Leaves}(\mathcal{T})} B_j^n$$

↙ "orthonormal basis corresponding to \mathcal{T} "

Choosing a dyadic partition

How do we choose which dyadic partition is best for a given signal $f(t)$?

Suppose $f(t)$ looks like this:



What would a "good" partition look like (qualitatively)?

We want an orthobasis B_T such that the decomposition

$$\{ \langle f, \theta \rangle \}_{\theta \in B_T}$$

is maximally concentrated.

(i.e. it gives the simplest description of $f(t)$).

To quantify this, we will assign a cost of a basis (partition) using an entropy measure:

$$\mathcal{C}(f, B_T) = - \sum_{\theta \in B_T} \frac{|\langle f, \theta \rangle|^2}{\|f\|_2^2} \cdot \log \left(\frac{|\langle f, \theta \rangle|^2}{\|f\|_2^2} \right)$$

$\mathcal{C}(f, B_T)$ is minimum (=0) when _____

$\mathcal{C}(f, B_T)$ is maximum when _____

Since the W_j^\wedge are \perp for $(j, n) \in \text{Leaves}(T)$ we can write

$$\mathcal{C}(f, B_T) = \sum_{(j, n) \in \text{Leaves}(T)} \mathcal{C}(f, B_j^\wedge)$$

$$B_j^\wedge = - \sum_{\theta \in B_j^\wedge} \frac{|\langle f, \theta \rangle|^2}{\|f\|_2^2} \cdot \log \left(\frac{|\langle f, \theta \rangle|^2}{\|f\|_2^2} \right)$$

Associated with each node in \mathcal{T} we have

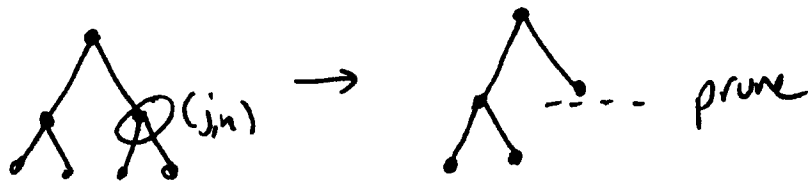
- an index (j, n) (scale, shift)
- a subspace W_j^n
- an orthobasis B_j^n (for W_j^n)
- a cost $\mathcal{C}(f, B_j^n)$
(given a signal $f(t)$)

The goal is given an $f(t)$, find the tree \mathcal{T} that minimizes the sum of the costs at the leaves.

$$\min_{\mathcal{T}} \sum_{(j,n) \in \text{Leaves}(\mathcal{T})} \mathcal{C}(f, B_j^n)$$

Of course, $\mathcal{E}(f, \mathcal{T})$ will change as we vary \mathcal{T} . But because the W_j^n are \perp for $(j, n) \in \text{Leaves}(\mathcal{T})$, collapsing* a pair of children W_{j+1}^{2n} and W_{j+1}^{2n+1} into their parent W_j^n does not affect the contributions at the other leaves.

Collapsing or pruning a tree at node (j, n) means we use B_j^n to span W_j^n instead of $B_{j+1}^{2n} \cup B_{j+1}^{2n+1}$



This allows us to decide:

"Which is better, B_j^n or $B_{j+1}^{2n} \cup B_{j+1}^{2n+1}$?"

independently from decisions in other subtrees.

We can then use a fast dynamic program to find the global minimum of $\mathcal{E}(f, \mathcal{B}_{\mathcal{T}})$ over all valid dyadic trees \mathcal{T} .

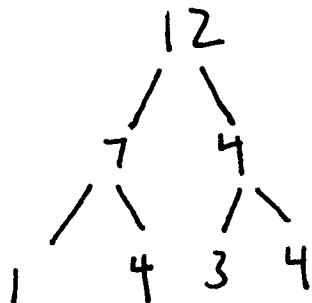
Example:

$J=2$. Say $\mathcal{L}(f, \mathcal{B}_0) = 12$

$\mathcal{L}(f, \mathcal{B}_1^0) = 7$ $\mathcal{L}(f, \mathcal{B}_1^1) = 4$

$\mathcal{L}(f, \mathcal{B}_2^0) = 1$ $\mathcal{L}(f, \mathcal{B}_2^1) = 4$ $\mathcal{L}(f, \mathcal{B}_2^2) = 3$

$\mathcal{L}(f, \mathcal{B}_2^3) = 4$



What is the best partition?

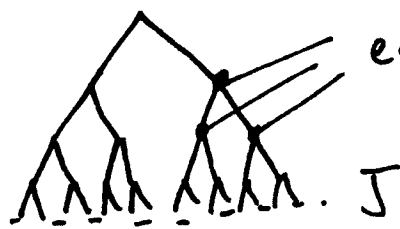
Optimization Algorithm (CART)

Maximum tree depth J

① Initialize the score S_j^n at each node on the tree with

$$S_j^n = \mathcal{L}(f, \mathcal{B}_j^n)$$

Initialize the tree \mathcal{T} as a full binary tree out to level J



each node has a score S_j^n

② For $j = J-1, J-2, \dots, 0$ and $n = 0, 1, \dots, 2^j - 1$ do

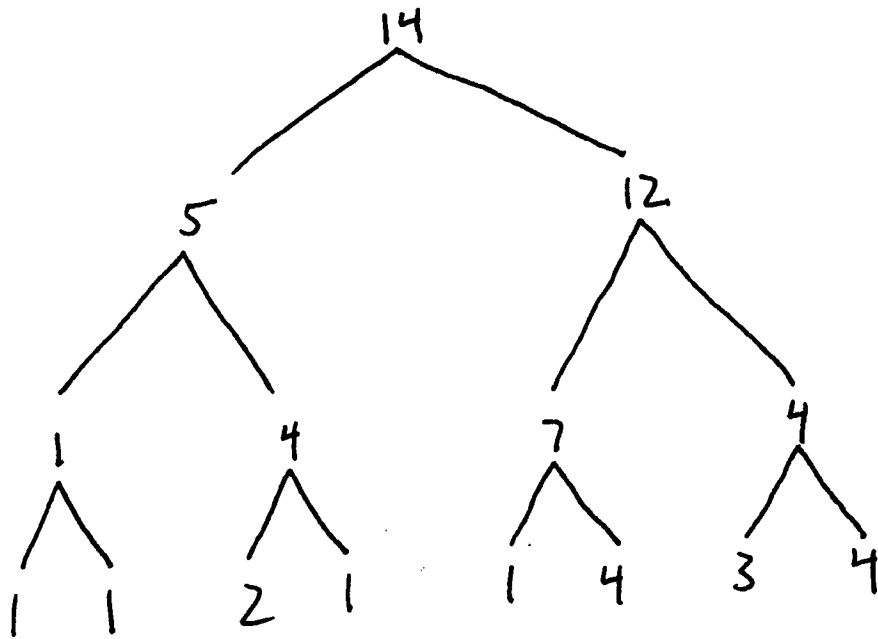
If $S_j^n \leq S_{j+1}^{2n} + S_{j+1}^{2n+1}$ then
prune tree at node (j, n)

else
set $S_j^n = S_{j+1}^{2n} + S_{j+1}^{2n+1}$

After we have traveled all the way up the tree, \mathcal{T} will correspond to the optimal cost/partition/basis

Example.

Suppose the $\mathcal{E}(f, B_j^n)$ are given by



Use CART to find the optimal tree / partition / basis.