

Non-orthogonal Bases & Frames

Reference: Mallat, Section 5.1

We have seen that if $\{\delta_n\}$ is an orthonormal basis (complete orthonormal sequence) for a Hilbert space H , we can "recover" (using the reproducing formula) any $f \in H$ from the sequence $\{\langle f, \delta_n \rangle\}$ in the most stable way imaginable (thanks to Parseval).

The questions arise:

Given a general sequence of vectors $\{\delta_n\}$

① When can we recover f from

$$\{\langle f, \delta_n \rangle\}_n = \begin{bmatrix} \langle f, \delta_1 \rangle \\ \langle f, \delta_2 \rangle \\ \vdots \\ \langle f, \delta_k \rangle \\ \vdots \end{bmatrix} ?$$

② How do you do it?

③ How stable is the recovery?

We will break these questions into two cases:

a) Non-redundant (Riesz bases)

The sequence $\{\delta_n\}$ is linearly independent.
Remove any of the δ_n from the sequence
and it is incomplete (will not span H)
 \Rightarrow there is a unique way to represent each $f \in H$.

b) Overcomplete (Frame)

The sequence $\{\delta_n\}$ is complete
and linearly dependent

\Rightarrow there are an infinite number of ways
to represent each $f \in H$.

The answer to ① is the same in both cases:

We can recover any f from $\{\langle f, \phi_n \rangle\}_{n \in T}$ if there exists

$$0 < A < B < \infty$$

such that

$$A \cdot \|f\|_H^2 \leq \sum_{n \in T} |\langle f, \phi_n \rangle|^2 \leq B \cdot \|f\|_H^2 \quad \text{iff } f \in T$$

This is something akin to the Parseval condition:
we require that $\sum_{n \in T} |\langle f, \phi_n \rangle|^2$ is close to $\|f\|_H^2$

The ratio B/A is the condition number of the representation.

Footnote: We will start using T to represent a general discrete index set.

In finite dimensional space,

$$T = \{1, 2, \dots, n\}$$

In infinite dimensional space, T is something which can be put in 1-to-1 correspondence with the integers, e.g.

$$T = \mathbb{Z}, \quad T = \mathbb{N}, \quad T = \mathbb{Z} \times \mathbb{Z}, \text{ etc.}$$

↑ natural numbers ↑ pairs of integers

Non-redundant systems (finite dimensions)

Let's start with $H = \mathbb{C}^n$ and a sequence
of $\theta_1, \theta_2, \dots, \theta_m \in \mathbb{C}^n$

$$f = \begin{bmatrix} f(1) \\ f(2) \\ \vdots \\ f(n) \end{bmatrix} \in \mathbb{C}^n \quad \alpha = \{\langle f, \theta_k \rangle\}_{k=1}^m = \begin{bmatrix} \langle f, \theta_1 \rangle \\ \langle f, \theta_2 \rangle \\ \vdots \\ \langle f, \theta_m \rangle \end{bmatrix} \in \mathbb{C}^m$$

Taking $\bar{\Phi} = \begin{bmatrix} \theta_1^* \\ \theta_2^* \\ \vdots \\ \theta_m^* \end{bmatrix}$ (the θ_n^* as rows)

We see that the matrix $\bar{\Phi} : \mathbb{C}^n \rightarrow \mathbb{C}^m$

$$\bar{\Phi} f = \alpha = \{\langle f, \theta_k \rangle\}_{k=1}^m$$

is the basis operator.

For the rows to be linearly independent, we need $m \leq n$

To be able to recover general f , we need $m \geq n$

i.e. we need $m = n$ and $\bar{\Phi}^{-1}$ to exist

Reproducing formula

$$f = \bar{\Phi}^{-1} \bar{\Phi} f \quad (\text{duh})$$

$$= \sum_{k=1}^n \langle f, \phi_k \rangle \tilde{\phi}_k$$

where $\tilde{\phi}_k$ are the columns of $\bar{\Phi}^{-1}$

Note:

$$\langle \tilde{\phi}_k, \phi_l \rangle = \begin{cases} 1 & k=l \\ 0 & \text{otherwise} \end{cases} \quad \left(\text{because } \bar{\Phi} \bar{\Phi}^{-1} = I \right) \text{ as well}$$

The pair $\{\tilde{\phi}_k\}_{k=1}^n, \{\phi_k\}_{k=1}^n$ is called a biorthogonal basis for \mathbb{C}^n .

Q1: In \mathbb{C}^n , given a biorthogonal basis $\{\phi_k\}, \{\tilde{\phi}_k\}$ what are the "best" A and B s.t.

$$A \cdot \|f\|^2 \leq \sum_{k=1}^n |\langle f, \phi_k \rangle|^2 \leq B \cdot \|f\|^2 ?$$

Q2: What are the best \tilde{A}, \tilde{B} s.t.

$$\tilde{A} \cdot \|f\|^2 \leq \sum_{k=1}^n |\langle f, \tilde{\phi}_k \rangle|^2 \leq \tilde{B} \cdot \|f\|^2 ?$$

Recall: The matrix $\Phi^* \Phi$ is symmetric (Hermitian) and positive-definite, so its eigenvectors are orthonormal and its eigenvalues are real.

In otherwords, the eigenvalue decomposition looks like

$$\Phi^* \Phi = U \Sigma U^*$$

where U is orthonormal ($U^* U = U U^* = I$) and Σ is diagonal with

$$\Sigma_{k,k} = \sigma_k = k^{\text{th}} \text{ largest eigenvalue of } \Phi^* \Phi$$

Note:

$$\begin{aligned} \sum_{k=1}^n |\langle f, \phi_k \rangle|^2 &= \langle \Phi f, \Phi f \rangle \\ &= \langle f, \Phi^* \Phi f \rangle \\ &= \langle f, U \Sigma U^* f \rangle \\ &= \langle U^* f, \Sigma U^* f \rangle \end{aligned}$$

Set $x = U^* f$, note $\|x\|^2 = \|f\|^2$ (U, U^* are \perp).

Then

$$\sum_{k=1}^n |\langle f, \alpha_k \rangle|^2 = \langle \alpha, \sum \alpha \rangle \\ = \sum_{k=1}^n \sigma_k |\alpha_k|^2$$

Since $\sigma_k > 0$

$$\sigma_{\min} \|f\|^2 \leq \sum_{k=1}^n \sigma_k |\alpha_k|^2 \leq \sigma_{\max} \cdot \sum_k |\alpha_k|^2 = \sigma_{\max} \|f\|^2$$

$$A = \sigma_{\min} \text{ (smallest eigenvalue of } \underline{\Phi}^* \underline{\Phi} \text{)} \\ B = \sigma_{\max} \text{ (largest eigenvalue of } \underline{\Phi}^* \underline{\Phi} \text{)}$$

Similarly,

$$\sum_{k=1}^n |\langle f, \tilde{\alpha}_k \rangle|^2 = \langle (\underline{\Phi}^{-1})^* f, (\underline{\Phi}^{-1})^* f \rangle \\ = \langle f, \underline{\Phi}^{-1} (\underline{\Phi}^{-1})^* f \rangle \\ = \langle f, (\underline{\Phi}^* \underline{\Phi})^{-1} f \rangle$$

$$\text{Since } (\underline{\Phi}^* \underline{\Phi})^{-1} = U \Sigma^{-1} U^*$$

$$\Rightarrow \tilde{A} = 1/\sigma_{\max}$$

$$\tilde{B} = 1/\sigma_{\min}$$

Stability

Suppose now that we perturb the coefficients
 $\{\langle f, \phi_k \rangle\}$.

Set $\lambda_k = \langle f, \phi_k \rangle + \varepsilon_k$

$$\bar{f} = \sum_{k=1}^n \lambda_k \tilde{\phi}_k = f + \sum_{k=1}^n \varepsilon_k \tilde{\phi}_k$$

Error $e = f - \bar{f} = \sum_k \varepsilon_k \tilde{\phi}_k = \Phi^{-1} \varepsilon$ $\left(\varepsilon = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix} \right)$

$$\|e\|^2 = \|\Phi^{-1} \varepsilon\|^2 \leq \frac{1}{A} \cdot \underbrace{\|\varepsilon\|^2}_{\text{total "noise" added to coeffs}}$$

error in reconstruction

If A is close to 1, the system is very stable
 (error does not "blow up")

Note: If $\|\phi_k\| = 1 \forall k$, then $A \leq 1 \leq B$.

Why? Prove on homework....

Infinite dimensions

In infinite dimensions, we have the same basic framework, but with infinite sequences

$$\Phi: H \rightarrow \ell_2(T)$$

$$\Phi[f] = \{\langle f, \vartheta_k \rangle\}_{k \in T}$$

Again, if $\exists 0 < A \leq B < \infty$

$$A \cdot \|f\|_H^2 \leq \sum_{k \in T} |\langle f, \vartheta_k \rangle_H|^2 \leq B \cdot \|f\|_H^2 \quad \forall f \in H$$

then we can reconstruct f from $\{\langle f, \vartheta_k \rangle_H\}_{k \in T}$

i.e. \exists another sequence $\{\tilde{\vartheta}_k\}_{k \in T}$ s.t.

$$f = \sum_{k \in T} \langle f, \vartheta_k \rangle \tilde{\vartheta}_k$$

$(\{\tilde{\vartheta}_k\}_{k \in T}$ is called the Riesz dual basis
to $\{\vartheta_k\}_{k \in T}\)$

and

$$\frac{1}{B} \cdot \|f\|_H^2 \leq \sum_{k \in T} |\langle f, \tilde{\vartheta}_k \rangle_H|^2 \leq \frac{1}{A} \cdot \|f\|_H^2$$

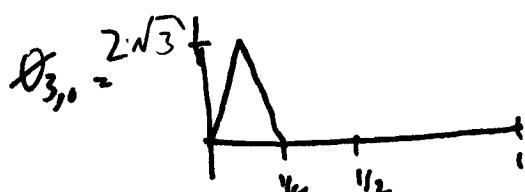
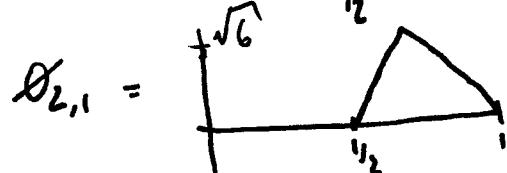
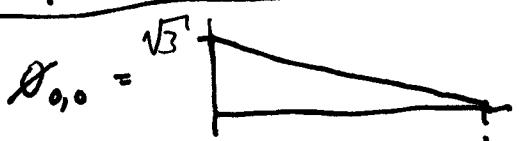
\Rightarrow the reconstruction is stable

One thing changes in infinite dimensions:
 We can have a "complete", linearly independent
 $\{\phi_n\}$ but have $A=0$.

Example: "Weighted Fourier Series" on $L_2(0, \beta)$

$$\{\phi_n\} = \left\{ \frac{1}{n} e^{j2\pi n t} \right\}_{n \in \mathbb{Z}}$$

Example w/ normalized ϕ_n :



If we cut this sequence
 off at N terms, the
 condition number
 $\frac{B}{A} \approx \sqrt{N}$
 (gets big)